Total No. of Printed Pages:2

SUBJECT CODE NO: H-194 FACULTY OF ENGINEERING AND TECHNOLOGY T.E. (Mechanical) CAD/CAM/CAE (REVISED)

[1 ime:	Inree	e Hours]	3: 0 U
N.B		Please check whether you have got the right question paper. i) Answer <u>any three</u> questions from each section. ii) Assume suitable data whenever necessary. iii) Figures to the right indicate full marks, iv) Draw neat sketches wherever necessary. Section A	O A A A A A A A A A A A A A A A A A A A
Q.1	a.	Explain how computer aided design procedure is superior to conventional design procedure?	07
	b.	Explain the importance of manufacturing database in CAD applications.	06
Q.2	a. b.	What is concatenation in transformation process explain with suitable example. Explain following modelling techniques. i) Parametric modelling ii) Constraint based modelling	06 07
		quare with its vertices. A(3,2), B(8,2), C(8,7) and D(3,7) is defined in 2D space, perform the ring transformations separately and show them on graph paper. Translation in X-direction by 2 units & 1 unit in Y-direction. Rotation about point A through an angle 90° anticlockwise, the axis of rotation is parallel to z-axis.	13
Q.4		Enlist different surface generation techniques & explain anyone in detail. Explain the characteristics of B-spline curves.	07 06
Q.5	a. b. c. d.	short notes on following. (any three) Bezier curve Product life cycle CAE Data input devices used in CAD systems Solid representation techniques used in CAD	14

Section B

Q.6	a.	Define FMS and explain various elements of FMS.	07
	b.	Define CIM and explain the concept of CIM industries.	06
Q.7	a.	Explain co-ordinate system for axis identification for following machines with neat sketch. i) Lathe M/C ii) Vertical milling M/C	07
	b.	Explain following G codes & M codes. G04, G27, G54.	06
Q.8	a.	Explain different robot programming methods.	07
	b.	Enlist the applications of FEA software & explain any one in detail.	06
Q.9	as sho	Tile milling operation is to be performed to generate the outline of the part and drill the holes; wn in figure 1, the part thickness is 15mm, cutter diameter as 10 mm dia & cutter speed	13

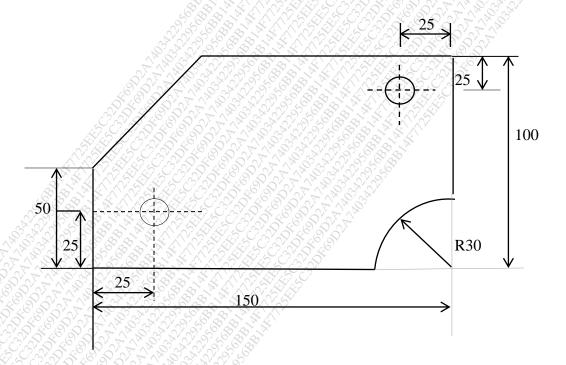


Figure.1

Q.10 Write short notes on (any two)

a. Group Technology

b. Fixed zero & floating zero

14

- c. Forward kinematics in robots