

SUBJECT CODE NO:- P-65
FACULTY OF ENGINEERING AND TECHNOLOGY
B.E.(MECH) Examination MAY/JUNE-2016
Automatic Control System
(Revised)

[Time:Three Hours]

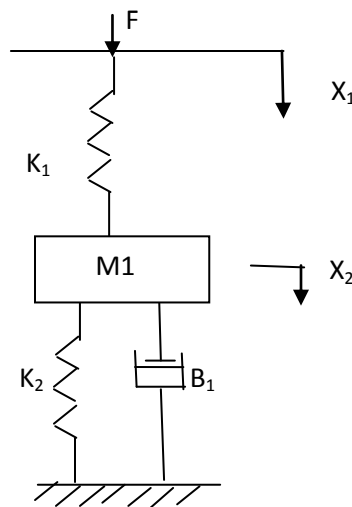
[Max Marks:80]

“Please check whether you have got the right question paper.”

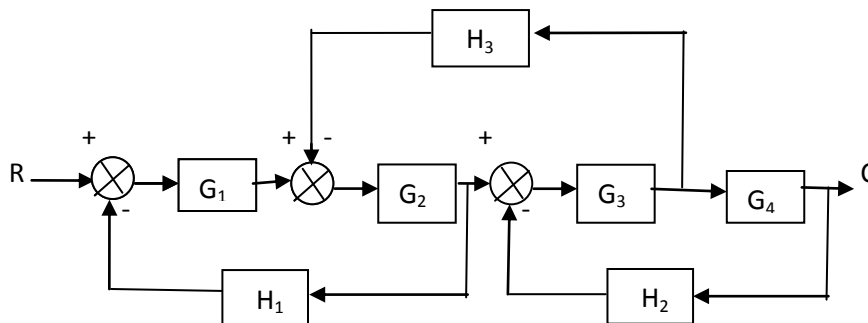
- N.B
- i) Solve any Three Questions from each Section.
 - ii) Draw neat Sketches if Required.
 - iii) Assume suitable data, if necessary.

Section A

- | | | |
|-----|--|----|
| Q.1 | a) What is Control System? Differentiate between Manual Vs. Automatic Control System. | 07 |
| | b) Give in detail Classification of Control System and explain any one Control System. | 06 |
| Q.2 | a) For the mechanical System as shown in fig. obtain direct analogous electrical ckt. | 07 |

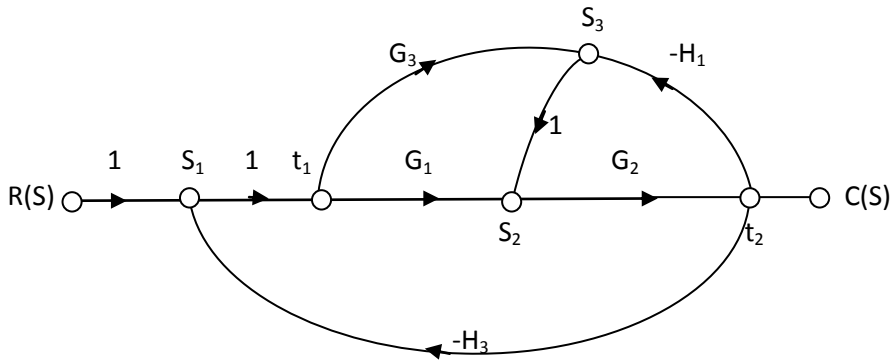


- | | | |
|-----|---|----|
| | b) Explain in detail Thermal System. | 06 |
| Q.3 | a) Determine the T.F for the system represented by block diagram as shown in fig. | 10 |



- | | | |
|--|--|----|
| | b) Write down advantages and disadvantages of Block diagram. | 04 |
|--|--|----|

Q.4 a) For the SFG shown in fig. determine the T.F 07



b) Explain ON/OFF Control action. 06

Q.5 a) Explain pneumatic P+I+D controller 07

b) Write a short note on Stepper Motor 06

Section B

Q.6 a) Explain the following Terms: 06

1) Steady state error 2) Stability of a System.

b) Define different time domain specification and show on suitable graph. 07

Q.7 a) Find the time domain specifications for 07

$$\frac{C(S)}{R(S)} = \frac{1}{s^2+s+1}$$

b) Write a short Note on types of standard input signals. 06

Q.8 a) Explain Nyquist stability criteria. 07

b) A unity feedback control system has 06

$$G(s) = \frac{K}{s(s^2+4s+5)(s+2)}$$

Determine Range of K so that system is stable

Q.9 a) Write a Note on Advantages of Bode plots 04

b) Given $G(s) = \frac{40(s+5)}{s(s+10)(s+2)}$ Draw the Bode plot and find the gain & phase margin. 09

Q.10 a) Draw the Root Loci for the following system $G(s).H(S) = \frac{K}{s(s+3)(s+5)}$ 09

b) Write short Note on use of MATLAB Software in control system. 05