

“Please check whether you have got the right question paper.”

- i) Q. No.1 and Q.No.6 are compulsory.
- ii) Solve any two questions from Q-2 to Q-5 and Q-7 to Q-10.
- iii) Assume suitable data wherever necessary.

SECTION-A

- Q.1 a) State essential parts of electrical drives .What are the functions of each part? 05
b) Explain in detail a four quadrant operation of a motor driving hoist load. 05
- Q.2 a) Why current sensing is required in electrical drives ?what are the common method of current sensing? 07
b) A drive has the following parameters : $T=150-0.1N$,N-mt,Where N is speed in rpm load torque $t_c=100N$ -mt 08
Initially the drive is operating in steady state . The characteristics of the load torque are changed to $T_L=-100N$ -mt
Calculate initial & final equilibrium speeds.
- Q.3 a) What are the different methods of speed control normally employed for d.c.motors ? Hence ,sketch the 07
characteristics of a seperately excited d.c motor based on these methods .Indicate clearly constant –torque and
constant power drive regions .
b) A seperately excited d.c motor Ts supplied from 250v,50Hz source through a single phase half wave converter. 08
Its field is fed through 1-phase semiconverter with zero degree firing angle delay. Motor resistance $r_a=0.7\Omega$ and
motor constant $=0.5V$ -se/rad. For rated load torque of 15N-mt at 1100rpm & for continuous ripple free currents
,determine
a) Firing angle delay of the armature converter .
b) RMS value of thyristor and free wheeling diode currents .
- Q.4 a) Describe how the speed of a d.c series motor can be controlled by means of a d.c chopper. 07
b) A d.c series motor , fed from 415v d.c source through a chopper , has the following parameters : 08
 $r_a=0.055\Omega$, $r_s=0.075\Omega$, $k=5.2 \times 10^{-3} Nm/Amp^2$. The average armature current of 210A is ripple free .for
a chopper duty cycle of 50% Determine i) motor torque ii) speed of the motor.
- Q.5 Write short notes on the following 15
a) Load equalization .
b) Regenerative braking .
c) Industrial applications of d.c motor .

SECTION-B

- Q.6 a) Explain in detail current source inverter fed induction motor drive . why CSI fed I.M drive is operated at a 10
constant rated flux ?
b) Explain static kramer drive.why has the static kramer drive is used for low range of speed control?
- Q.7 a) In a stator frequency control of a 3-phase induction motor , explain why 07
i) Ratio V/f is maintained constant for speed below base speed.
ii) Terminal voltage is maintained constant for speeds above base speed.
b) A 2.85kw ,415v ,50Hz ,4 pole , 1370rpm ,delta connected squirrel cage induction motor has following 08
parameters referred to the stator , $r_1=2.1\Omega$, $r_2=5.5\Omega$, $x_1=x_2=5.5\Omega$, $x_m=82\Omega$.motor speed is controlled
by stator voltage control when driving a fan load it runs at rated speed at rated voltage .calculate ,
i) Motor terminal voltage , current x torque at 1250 rpm &
ii) Motor speed , current & torque for the terminal voltage of 325v.

- Q.8 a) Explain in detail true synchronous mode and self control mode for variable frequency control of synchronous motor 07
- b) A 20kw, 3 phase, 440v, 4 pole, delta connected permanent magnet synchronous motor has following parameters ; $x_s = 5\Omega$, $R_s = 0\Omega$, *rated p.f* = 1.0 machine is controlled by variable frequency control at a constant (v/f) ratio. Calculate, Armature current, torque angle, and power factor at half full load torque and 750 rpm. 08
- Q.9 a) Explain in detail, why the load commutated inverter fed synchronous motor drive is found suitable for high power applications 07
- b) Describe the operation of brushless d.c motor drive. State its advantage over a low cost three phase brushless d.c motor drive 08
- Q.10 Write short note on the following : 15
- a) PWM controlled induction motor drive .
 - b) Industrial application of A.C Drives.
 - c) Brushless d.c. motor drives for servo applications