## SUBJECT CODE NO:- P-20 FACULTY OF ENGINEERING AND TECHNOLOGY B.E.(EEP/EEE/EE) Examination May/June 2017 Electrical Drives (Revised)

| [Time: Three Hours] |                    |  |      |  |  |  |
|---------------------|--------------------|--|------|--|--|--|
|                     |                    | Please check whether you have got the right question paper.  |      |  |  |  |
| N.B                 |                    | i) Q. No.1 from section A and Q.No.6 from section B are compulsory.  |      |  |  |  |
|                     |                    | ii) Attempt any two questions from Q.No.2 to Q.No.5 and any two questions from Q.No.7 to Q.No.10.  | , P  |  |  |  |
|                     |                    | iii) Assume suitable data whenever necessary.  |      |  |  |  |
|                     |                    | Section A  |      |  |  |  |
| Q.1                 | Attempt any FIVE:- |  | 10   |  |  |  |
|                     | a) .               | What is meant by electric drives?  |      |  |  |  |
|                     | b)                 | What is meant by "load equalization"   |      |  |  |  |
|                     | c)                 | State essential parts of electric drives.  |      |  |  |  |
|                     | d)                 | What are the choices of electrical drives?   |      |  |  |  |
|                     | e)                 | What is meant by regenerative braking?   |      |  |  |  |
|                     | f)                 | What is called continuous and discontinuous conduction?  |      |  |  |  |
|                     | g)                 | Give some applications of DC drives.   |      |  |  |  |
| Q.2                 | a)                 | Derive the expression to find the equivalent load torque and equivalent inertia of loads in translational and rotational motion.   | 08   |  |  |  |
|                     | b)                 | Prove that torque developed by the motor is given by.  | 07   |  |  |  |
|                     | •                  | $T = T_1 + j \frac{d_{wm}}{d_f} + W_{m} \frac{\dot{d}_j}{d_t}$   |      |  |  |  |
| Q.3                 | a)                 | Describe relative merits and demerits of four quadrant D.C. drives employing Non-circulating and circulating current dual convertors.  | 80 k |  |  |  |
|                     | (b)                | Describe how the speed of a dc series motor can be controlled by means of a dc chopper.  | 07   |  |  |  |
| Q.4                 | a)                 | A fully controlled rectifier is feeding a separately excited motor driving a friction load. Motor is operating in steady state with a rectifier firing angle of $30^{\circ}$ , Firing angle is now changed from $30^{\circ}$ to $60^{\circ}$ . Explain how the motor current and speed will change with time. Draw relevant waveform |      |  |  |  |
|                     | (b)                | Explain current limit control in detail with bock diagram.   | 07   |  |  |  |
| Q.5                 | Write              | short notes on the following:-   | 15   |  |  |  |
|                     | (a)                | Phase locked loop control.   |      |  |  |  |
|                     | (b)                | Constant torque and constant power control.  |      |  |  |  |
|                     | 67.00              | Change fod DC drives   |      |  |  |  |

## Section B

| Q.6  | Answer any FIVE:- |   |         |
|------|-------------------|---|---------|
|      | a)                | What are the advantages of squirrel cage induction motor over dc motor.   |         |
|      | b)                | What is meant by soft start?  | X 75 95 |
|      | c)                | What do you meant by self-control mode in synchronous motor?  |         |
|      | d)                | Mention the special features of BLDC motors.  |         |
|      | e)                | What is meant by V/F control?   |         |
|      | f)                | What do you meant by self-control mode in synchronous motor?  |         |
| Q.7  | a)                | 3 Kw, 400 V, 50 Hz, 4 pole 1370 rpm, delta connected squirrel cage induction motor has the following parameters referred to stator.       | 08      |
|      |                   | $R_s = 2\Omega$ , $X_s = X'_r = 5\Omega$ , $R'_r = 5\Omega$ , $X_m = 90\Omega$  |         |
|      |                   | Motor speed is controlled by stator voltage control. When driving a fan load it runs of rated speed at rated voltage, calculate.          |         |
|      |                   | <ol> <li>Motor terminal voltage, current and torque of 1200 rpm.</li> </ol>   |         |
|      | b)                | Explain the operation of brushless d.c. motor drive and its applications.   | 07      |
| Q.8  | a)                | Explain the operation of current source invertors fed induction motor drive.  | 07      |
|      | b)                | Explain in detail, why the load commutated invertor fed synchronous motor drive is found suitable for high power applications.            | 08      |
| Q.9  | a)                | In a stator frequency control of a 3-phase induction motor, explain why.  i. Ratio V/F is maintained constant for speed below base speed. | 08      |
|      | i                 | i. Terminal voltage s maintained constant for speeds above base speeds.   |         |
|      | c)                | Explain in detail with relevant circuit diagram why cycloconvertors control is suitable only for I speed drives?                          | low 07  |
| 0.40 | on<br>On          |   | 15      |
| Q.10 | 2,0               | Write short notes on the following:-  | 15      |
|      |                   | Advantages of BLDC over conventional DC motor.  |         |
|      |                   | Synchronous motor drive.  |         |
|      | (A) (A) (G) (A)   | Applications and advantages of AC drives  |         |